

Heterogenous investors in energy system models

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Solar energy in Germany – the physical facts and the political questions Annual solar

Motivation

- Where should investment in PV be made?
- Where are investments actually made?
- Who decides about investments?

Motivation & objective

Motivation

- **Increasing shares of renewables**
	- ➢ Higher variations of net load within days (and between days)

➢ *More distributed generation*

- ➢ at least for rooftop PV and in countries like Germany
- ➢ Also **distributed flexibilities**

➢Notably electric vehicles

➢ **Heterogenous investments and investors**

- ➢ Partly heterogeneity of technology potentials and preferences
- \triangleright Partly limited knowledge of planners/modellers
- ➢ **Standard energy system models do not cope with these investors**
	- \triangleright Linear programs subject to penny switching
	- ➢ Differentiation by investment opportunities (sites and technology types) possible,
	- ➢ yet leads to large models and still unsatisfactory representation of individual decision making
	- ➢ **Objective: develop an alternative approach to cope with heterogenous investments**

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Status quo: Energy system models

State of the Art

- **Large-scale optimization models** to model electricity and other energy systems
	- − Mostly formulated as linear programs or mixed integer linear programs
- Focus on **generation expansion** and **operations**,
	- − Generally limited detail regarding grid modelling
- Examples of long-standing energy system models:
	- − **MARKAL** (Fishbone and Abilock, 1981), **TIMES** (Loulou, 2008; Loulou and Labriet, 2008)
	- − Traditionally making use of only limited number of time slices (representative hours)
- Other examples
	- − E2M2s cf. (Swider and Weber, 2007; Spiecker, Vogel and Weber, 2013)
	- − PERSEUS (Rosen, Tietze-Stöckinger and Rentz, 2007)
	- − REMIX (Scholz, 2012; Gils et al. 2017)
	- − JHSMINE (Munoz et al. 2014, Xu and Hobbs 2021)
	- \triangleright Often more detailed temporal resolution, up to hourly resolution
	- \triangleright But long computation times and/or limitations regarding computational details

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Extensions to cope with heterogeneity

- **Differentiate technologies and/or applications** within energy system models, e.g.
	- − Solar energy use differentiated by orientation of roofs
	- − Heating systems by building types
- **Separate detailed modelling of** (geographical) distribution of **renewables and demand**, e.g.

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- − Renewable potentials and land use restrictions, e.g. renewable ninja (Pfenninger, Staffel 2016)
- − Models for heating systems in buildings, e.g. HeatSim (Bauermann 2016)
- **Iterative coupling** of **energy demand** and **system models**, e.g.
	- − Heating systems & electricity markets (Bauermann et al. 2014)
	- − Models of demand flexibility & electricity systems (Misconel et al. 2023)

➢ **Why not integrate them?**

Consumer decisions as optimization models - discrete choice models

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State of the Art

- Category of models popularized by Nobel laureate Daniel McFadden and others
	- − Describe optimal choices under stochastic utility
	- − Diverse specifications, notably logit and probit models
	- − Logit specification presents advantage of analytical formulations
- Standard stochastic utility formulation

 $U_i = V_i + \varepsilon_i$

Energy Markets

- − Consumers choose among alternatives *i*
- − Optimal individual choice: highest sum of observable and stochastic utility
- Corresponding choice probability or in case of binary choices (adoption yes/no)

$$
Prob_i = \frac{e^{V_i}}{\sum_j e^{V_j}} \qquad \qquad Prob_i = \frac{1}{1 + e^{-V_i}}
$$

Corresponding expected indirect utility function: LogExpSum (cf. Small & Rosen 1981) $E[U_i] = \ln(e^{V_i} + 1)$

Choice-based energy system modelling

- Discrete choice models
- **Energy system models**

Choice-based energy system modelling

Key advantages:

- More **"realism"** in energy system models
- Align the "central planner paradigm" of energy system models with the distributed decision making of the energy transition

Key challenges:

- **Non-linear** model
- Efficient **solution algorithms**

Note on terminology:

■ Term coined in analogy to "Choice-based facility location planning" (Müller 2023, based on Benati 1999, Benati and Hansen 2002, Haase 2009, Haase and Müller 2014)

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➢ Analogy also in two-level problem structure

Methodological basis: Agent-based welfare maximization

Mathematical problem formulation

Microeconomic background:

- Equivalence of market outcomes under perfect (or working) competition and optimum reached by social planner
- **Welfare** (in partial equilibrium) corresponds to **sum of consumer**(s) **surplus** and **producer**(s) **surplus**

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Basic idea:

- 1) Formulation of surpluses (respectively money-metric utility) for all agents
- 2) Summation of surpluses
- 3) Elimination of transfer payments (and the corresponding prices) in the aggregated surplus

First implementation:

 \triangleright Focus on transformation and capacity constraints

General agent in energy system models

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Mathematical problem formulation

Overall objective function and agent surpluses

Mathematical problem formulation

Welfare:

$$
\max_{d_t, K_i, y_{i,t}} W
$$

$$
W = S^C(d_t) + \sum_i S^{CvP}(K_i, y_{i,t}) + \sum_j S_j^{RE}(\pi_j, y_{j,t})
$$

Consumer surplus:

$$
S^{C}(d_{t}) = \sum_{t} (V - p_{t}) \cdot \Delta t \cdot d_{t}
$$

Conventional producer surplus:

Utility: represented by VOLL Cost: based on paid price

$$
S_i^{CvP}(K_i, y_{i,t}) = \sum_t (p_t - c_i^{op}) \cdot \Delta t \cdot y_{i,t} - c_i^{inv} \cdot K_i
$$

Revenue: based on received price Cost: including operational and investment cost

Renewable producer surplus:

 $S_j^{RE}(\pi_j, \varphi_{j,t}) = ...$

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List of symbols:

- index conventional producers
- index renewable producers
- index time steps
- c_i^{op} operational cost tech *i*
- d_t (realised) demand time t
- K_i capacity tech i
- p_t price time t
- S^{xyz} economic surplus group xyz
- V value of lost load (VOLL)
- W welfare
- $y_{i,t}$ production tech *i*, time *t*

 Δt time step length

Constraints

Methodology

Agent-specific constraints: Demand:

$$
d_t \cdot \Delta t + s_t \cdot \Delta t = D_t \cdot \Delta t \quad \forall t
$$

Conventional capacity:

 $y_{i,t} \cdot \Delta t \leq K_i \cdot \Delta t \quad \forall i \; \forall t$

List of symbols (continued):

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 D_t planned demand (load) $s_t\;$ load shedding

Overarching constraints:

Market clearing:

$$
d_t \cdot \Delta t = \sum_i y_{i,t} \cdot \Delta t + \sum_j K_j^{max} \varphi_{j,t} \cdot \pi_j \cdot \Delta t - r_t \cdot \Delta t \quad \forall t
$$

 K_j^{max} maximum potential tech j r_t renewable curtailment at time t π_i probability of invest in tech j $\varphi_{i,t}$ generation profile tech j

Objective function – focus on renewable producer surplus

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1

 $\beta e^{-\beta \varepsilon}$

=

 π

 $\beta\sqrt{3}$

Key properties of the aggregate optimization problem

Solution approach

■ Proposition 1:

Aggregation of surpluses of generalised price-taking agents leads to a **non-linear welfare maximization problem** in standard primal variables

Proposition 2:

This non-linear welfare maximization problem is **concave**

• Proposition 3:

The non-linear concave optimization problem may be **reformulated** as an **exponential cone problem**

Proposition 4 (tentative):

Higher heterogeneity/entropy (as measured by parameter $\frac{1}{\beta}$) increases c.p. welfare if Prob<0.5 and decreases welfare if Prob>0.5

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Proposition 1 – non-linear welfare maximization

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Welfare:

$$
W = S^{C}(d_{t}) + \sum_{i} S^{conv}(K_{i}, y_{i,t}) + \sum_{j} S_{j}^{RE}(\pi_{j}, y_{j,t})
$$

\n
$$
= \sum_{t} (V - p_{t}) \cdot \Delta t \cdot d_{t} + \sum_{i} (\sum_{t} (p_{t} - c_{i}^{op}) \cdot \Delta t \cdot y_{i,t} - c_{i}^{inv} \cdot K_{i}) + \sum_{j} \left(\sum_{t} (p_{t} - c_{j}^{op}) \cdot \Delta t \cdot \varphi_{j,t} - c_{j}^{inv} \right) K_{j}^{max} \pi_{j} + \sum_{j} H(\pi_{j}) K_{j}^{max} \frac{1}{\beta}
$$

\nConventional producer surplus
\nCollection of terms with p_{t} :
\n
$$
\sum_{t} \left(p_{t} \cdot \Delta t \cdot \left(-d_{t} + \sum_{i} y_{i,t} + \sum_{j} \varphi_{j,t} K_{j}^{max} \pi_{j} \right) \right) = \sum_{t} p_{t} \cdot \Delta t \cdot r_{t}
$$

 $= 0$ under standard market and renewable assumptions

Revised aggregate welfare:

$$
W = -\left(\sum_{t} \Delta t \cdot \left(V \cdot s_t + \sum_{i} c_i^{op} y_{i,t}\right) + \sum_{i} c_i^{inv} K_i + \sum_{j} c_j^{inv} K_j^{max} \pi_j\right) + \sum_{j} H(\pi_j) K_j^{max} \frac{1}{\beta}
$$

 \triangleright elimination of dual variable p_t , equivalent to cost minimization corrected for heterogeneity term

Proposition 2 – concave problem

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Objective function:

$$
W = -\left(\sum_{t} \Delta t \cdot \left(V \cdot s_t + \sum_{i} c_i^{op} y_{i,t}\right) + \sum_{i} c_i^{inv} K_i + \sum_{j} c_j^{inv} K_j^{max} \pi_j\right) + \sum_{j} H(\pi_j) K_j^{max} \frac{1}{\beta}
$$

Constraints:

Demand:

$$
d_t \cdot \Delta t + s_t \cdot \Delta t = D_t \cdot \Delta t \quad \forall t
$$

Conventional capacity:

$$
y_{i,t} \cdot \Delta t \le K_i \cdot \Delta t \quad \forall i \ \forall t
$$

Market clearing:

$$
d_t \cdot \Delta t = \sum_i y_{i,t} \cdot \Delta t + \sum_j K_j^{max} \varphi_{j,t} \cdot \pi_j \cdot \Delta t - r_t \cdot \Delta t \quad \forall t
$$

 \triangleright Objective function is non-linear in π_j , everything else is linear Derivatives:

$$
\frac{\partial W}{\partial \pi_j} = -c_j^{inv} K_j^{max} - (\ln \pi_j + 1 - \ln(1 - \pi_j) - 1) K_j^{max} \frac{1}{\beta}
$$

$$
\frac{\partial^2 W}{\partial \pi_j^2} = -\left(\frac{1}{\pi_j} + \frac{1}{1 - \pi_j}\right) K_j^{max} \frac{1}{\beta} < 0 \quad \forall \pi_j \in (0, 1) \qquad \frac{\partial^2 W}{\partial \pi_j \partial \pi_i} = 0 \quad \forall j \neq i
$$

$$
\implies \text{Objective function is concave, as are the constraints}
$$

 \cup of converging is concave, as are the constraints

Proposition 3 – reformulation with exponential cones

Solution approach

Definition exponential cone:

$$
\mathcal{K}_{exp} = \left\{ (x_1, x_2, x_3) \middle| x_1 \ge x_2 e^{\frac{x_3}{x_2}}, x_2 > 0 \right\} \cup \left\{ (x_1, 0, x_3) \middle| x_1 \ge 0, x_3 \le 0 \right\}
$$

Note equivalence for key inequality:

$$
x_1 \ge x_2 e^{\frac{x_3}{x_2}} \Leftrightarrow \ln(x_1) \ge \ln(x_2) + \frac{x_3}{x_2} \Leftrightarrow x_3 \le x_2 \ln(x_1) - x_2 \ln(x_2)
$$

Also

$$
\max_{\pi_j} A(\pi_j, \dots) + H(\pi_j) \Leftrightarrow \max_{\pi_j} A(\pi_j, \dots) + E_j + E_j^{cp} | E_j + E_j^{cp} \le H(\pi_j)
$$

Then

$$
E_j \le -\pi_j \ln \pi_j \Leftrightarrow (1, \pi_j, E_j) \in \mathcal{K}_{exp}
$$

Analoguously

$$
E_j^{cp} \le -\pi_j^{cp} \ln \pi_j^{cp} \Leftrightarrow \left(1, \pi_j^{cp}, E_j^{cp}\right) \in \mathcal{K}_{exp}
$$

With additional constraint

$$
\pi_j + \pi_j^{cp} = 1
$$

19 ➢ A **standard solver**, namely **MOSEK**, may be used to solve the non-linear concave optimization problem ➢ **Non-linear term in objective function** may be **replaced by two restrictions on exponential cones**

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First application: stylized German model

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Application

- Based on data from Poestges et al. (2019), publically available under zenodo: <https://zenodo.org/record/3674005>
	- − Reference year for weather and demand 2015
	- − $CO₂$ price 100 €/t $CO₂$
	- − Wind energy potentials adjusted to current German law, requiring 2 % of land area to be made available
- Spatial resolution: Germany split in five TSO regions (cf. Figure)
- Temporal resolution: 1 year in 8760 hours
- Investments in the following technologies:
	- − CCGT
	- − OCGT
	- − PV
	- − Wind onshore
- No grid restrictions, only small transport fee $(0.01 \in \angle MWh)$

■ Scale parameter for heterogeneity $s = \frac{1}{\rho}$ $\frac{1}{\beta} = 0.1 \cdot c_j^{inv}$ **Energy Markets**

Computation statistics

Application

- Computations performed on a Notebook running on Windows (13th Gen Intel(R) Core(TM) i7-1365U, 1.80 GHz, 32 GB RAM)
- Software used: GAMS release 46.2.0 & MOSEK solver version 10.1.27

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Application

Regional energy balances

Application

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Cost perspective

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Application

• Modelling framework provides an **innovative approach** to model distributed electricity systems

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- Copes with heterogeneity based on an established **stochastic utility framework**
- First application **highlights differences** to conventional linear programs
- **Results to be explored further** in more detailed applications
- Heterogeneity **parameters** may be determined from **empirical observations**

Thank you for your attention!

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References

